Uncertainty Analysis for Broadband Solar Radiometric Instrumentation Calibrations and Measurements: An Update

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Uncertainty Analysis for Broadband Solar Radiometric Instrumentation Calibrations and Measurements: An Update

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Abstract

Emphasis on solar renewable energy technologies in the 1970's, and the concern about the Earth's radiation balance related to the possibility of climate change in the 1990's raised the importance of broadband solar radiation measurements. In parallel, standardized methods of uncertainty analysis and reporting have been developed. Historical and updated uncertainties are based on the present international standardized uncertainty analysis method. Despite the fact that new and sometimes overlooked sources of uncertainty have been recently identified, uncertainty in broadband solar radiometric instrumentation remains at 3% to 5% for pyranometers, and 2% to 3% for pyrheliometers. Improvements in characterizing correction functions for radiometer data may reduce total uncertainty. We analyze the theoretical standardized uncertainty sensitivity coefficients for the instrumentation calibration measurement equation and highlight the single parameter (thermal offset voltages), which contributes the most to the observed calibration responsivities.

Introduction

Uncertainty requirements vary for assessing solar radiation resources for solar energy systems, or investigating climate change. For renewable energy assessment, uncertainty of a few percent may be adequate. One watt per square meter (W/m²) uncertainty is needed to determine radiative forcings in climate change. Uncertainty in the calibration of pyrheliometers (measuring the solar direct beam), and pyranometers (measuring the diffuse sky and total sky, or global [combined direct and diffuse] radiation) determines the uncertainty in measurements they report

Radiometer Calibrations

The World Radiometric Reference (WRR) is the standard for solar radiometers [1, 2], and embodies the International System of Units (SI) of solar irradiance. Romero et al. [3] showed equivalence of better than $\pm 0.05\%$ between WRR and the SI radiation scale. The WRR is transferred with an uncertainty of $\pm 0.3\%$ to national reference absolute cavity radiometers (ACR) every five years at the World Radiation Centre in Davos Switzerland [4, 5]. Pyrheliometer responsivities (Rs, output signal per stimulus unit) are derived by direct comparisons with reference ACRs traceable to WRR [4]. Pyranometer responsivities are often derived from the "component summation" technique, where a reference global irradiance (G) is derived from an absolute cavity radiometer beam measurement (B) and shaded pyranometer (diffuse) measurement (D) using $G = B \cos(z) + D$.

Responsivity (Rsd) for a diffuse-measuring reference pyranometer is derived in a shade-unshade calibration using Rsd = (U-S)/[B*Cos(z)] where U and S are the unshaded and shaded output voltages from the sensor, z is the zenith angle, and B is measured by

an ACR[6] Procedures for this calibration are described in the American Society for Testing and Materials Standard E-913 [6]. NREL proposed shade-unshade pyranometer calibration using an average responsivity at 45° zenith angle for three instrument azimuth angles to integrate over geometric response variations [7]. A modification includes a continuously shaded, or control pyranometer, and 60° rotation angles [8]. Regression fits of responsivities to zenith angle, Rs(z) determine six Rs(45°), the mean of which is used for the reference diffuse (shaded pyranometer) in a component summation calibration.

Uncertainty Analysis

Measurements only approximate the quantity being measured, and are incomplete without a quantitative uncertainty. The Guide to Measurement Uncertainty (GUM) of the International Bureau of Weights and Measures [9] is the accepted guide for measurement uncertainty. The GUM defines Type A uncertainty values as derived from statistical methods, and Type B sources as evaluated by "other means", such as scientific judgment, experience, specifications, comparisons, or calibration data.

Every element of a measurement system contributes elements of uncertainty. When a result, R, is functionally dependent upon several i=1,...,n variables, x_i , the familiar propagation of error formula $U^2 = \sum_i (\partial_{xi} R \cdot e_{xi})^2$ is used. U is the uncertainty in the resultant, e_{xi} is the estimated uncertainty in variable x_i , and $\partial_{xi}R$ is the partial derivative of the response R with respect to variable x_i , called the sensitivity function for variable x_i .

Previously [10,11] pyranometer calibration uncertainty treated sources of uncertainty in terms of "random" and "bias" types. Total uncertainty U was computed from: $U^2 = \Sigma \text{ (Bias)}^2 + \Sigma (2*\text{Random})^2$. The resulting uncertainty in calibration of pyranometer responsivity and field measurements was 2.4%, and 5%, respectively. The GUM replaces the factor of two with a "coverage factor", k and $U^2 = \Sigma \text{ (Type B)}^2 + \Sigma (k*\text{ Type A})^2$. For small (n<20) samples, k may be selected from the student's t-distribution [12]. U is the "Expanded Uncertainty", and k is usually in the range of 2 to 3, for confidence intervals of 95% and 99%, respectively [12].

Recently Identified Uncertainty Sources: Thermal Offset

World Climate Change Research Program participants and others [13, 14] have identified thermal offsets in thermopile pyranometers that measure diffuse radiation with all-black sensors [15, 16]. The offsets appear as negative signals at night, and clear sky diffuse irradiances lower than expected with pure Rayliegh scattering [16]. Cold junctions of "all-black" thermopiles are in a different thermal environment than absorbing junctions, while in black-and-white sensors, reference and absorbing junctions are in a similar thermal environment. The latter radiometers have low (~1 to 2 W/m²) offsets and produce more accurate diffuse measurements [17].

Sensitivity Functions

Reference diffuse radiometer responsivity uncertainty, U_{shade} , computed from the propagation of error formula for the shade-unshade calibration equation is:

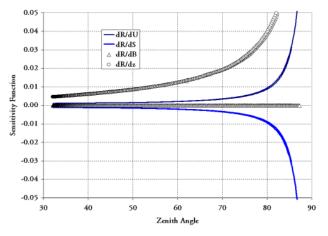
$$U_{\text{shade}}^2 = (\partial_U Rs * e_U)^2 + (\partial_S Rs * e_S)^2 + (\partial_B Rs * e_B)^2 + (\partial_z Rs * e_z)^2$$

where e_U is the uncertainty in unshaded voltage, etc. For the component summation

equation, the propagation of error formula becomes:

$$U_{sum}^{2} = (\partial_{U}Rs * e_{U})^{2} + (\partial_{D}Rs * e_{D})^{2} + (\partial_{B}Rs * e_{B})^{2} + (\partial_{z}Rs * e_{z})^{2}$$

For a data set of pyranometer voltages, beam and (black and white) diffuse irradiances, figure 3a and 3b show sensitivity functions for each of the calibration types.



0.030 0.00010 80000.0 0.025 Volt and Zenith Dependence 0.020 dR/dz 0.00003 □ dR/dB dR/dD 0.015 -0.00003 0.010 -0.00005 0.005 -0.00008 -0.00010 0.000 Zenith Angle

Fig. 3a. Sensitivity functions for shade-unshade calibration. Note sensitivity to shade (negative line) and unshade (positive line) voltages are mirror image of each other. Greatest sensitivity is to zenith angle (circles). Negligible sensitivity to beam uncertainty.

Fig. 3b. Sensitivity functions for component summation calibration. Sensitivity to beam (square) and diffuse (circle) irradiances are much less (right scale) than to voltage (heavy line) and zenith angle (light line) (left scale).

Total uncertainties depend on the product of sensitivity functions and e_i . The most important contributions come from the e_V , e_U and e_S , which must include estimates of the thermal offset as well as data logger measurement uncertainty (typically < 10 uV). For an (all-black sensor) pyranometer responsivity of 7.0 mV per 1000 Wm⁻² a 70 uV offset corresponds to an irradiance of -10 W/m⁻². Figures 4a and 4b show the percent uncertainty in responsivity for increasing uncertainty in voltage measurements for e_B = 4.0 Wm⁻², e_z = 0.06°, e_D = 2.0 Wm⁻² (black and white sensor). Note the component summation technique has relatively lower uncertainties, because there is only the one voltage component, as opposed to two in the shade-unshade technique.

Responsivity Functions

Figure 5 shows the responsivity of a pyranometer versus zenith angle using NREL component summation calibration [18]. Analysis of the uncertainty in each pyranometer calibration responsivity *point* in figure 5 is summarized in table 1. A responsivity function derived from such data with the *offsets embedded in the result* can be used to retrieve the most accurate irradiance from a pyranometer.

The far right curve in figure 4b assumes $e_V = \text{data logger uncertainty (9 uV)}$ only, and "ignores" the offset voltage, which is "built into" the calibration result. The expanded uncertainty with k=2 for each point in figure 5 is 0.7%. This is the smallest uncertainty that can be expected of a pyranometer under conditions identical to the calibration conditions.

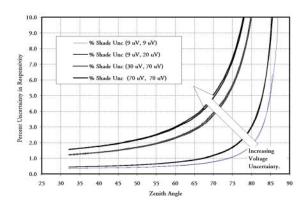


Fig. 4a. Total Uncertainty in shade-unshade calibrations versus zenith angle for various uncertainties in voltage measurement with fixed beam (4 Wm⁻²) and z angle (0.06°) uncertainty. Arguments in parenthesis are uncertainty in shade unshade voltages, respectively

The responsivity for a particular zenith angle, m, at the time of measurement, Rs(m), can be obtained from a fit to the calibration response curve, using forty-six 2° wide zenith angle intervals, of the form:

angle intervals, of the form:
$$Rs(z)_{AM/PM} = \sum_{i=0}^{i=46} a_i \bullet Cos^i(z)$$

where a_i are 46 coefficients for each morning and afternoon set of z. With this approach, uncertainty of $\pm 1.5\%$ in measured pyranometer data can be achieved. Using a responsivity at a given zo, $Rs(z_o)$, the uncertainty in a measurement of global irradiance will change as the difference between $Rs(z_o)$ and Rs(m) changes, and may grow to more than 10% for zenith angles sufficiently different.

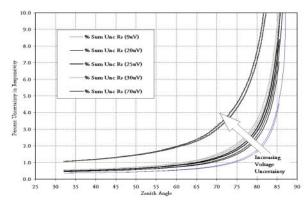


Fig. 4b. Total uncertainty in component sum calibrations as a function of zenith angle for various uncertainties in voltage measurement (in parenthesis), and fixed beam (4 Wm⁻²), zenith angle (0.06°), and diffuse (2 Wm⁻²) uncertainty.

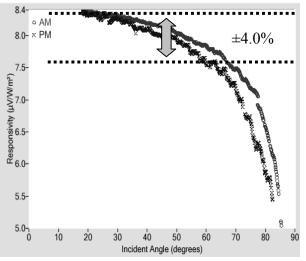


Fig. 5. Pyranometer responsivity versus solar zenith angle. Dotted lines are +4% and -4% away from mean Rs(45°).

Conclusion

Sensitivity functions for shade-unshade and component summation pyranometer calibration techniques show that uncertainties in signal voltages, including thermal offset voltages, affect Rs(z) the most, when beam, diffuse, and zenith angle errors are minimal. Either calibration can map geometric and thermal response. The range of deviations in Rs(z) produce uncertainty in measured data that is highly dependant on the responsivity chosen. The best measured data (U \sim 1.5%) is that using Rs(z) for the zenith angle at the time of the measurement. That responsivity can be obtained from a fit of Rs (z). Otherwise, uncertainty of 3% to 5% or more, can occur in measured global solar radiation data.

Table 1. Uncertainty for each measured responsivity point in figure 5.

Source	Type B %	2*Type A %	Combined (RSS)
WRR Ref. Cav (±4 Wm ⁻²)	0.300	0.200	0.50
Compute Z, $Cos(Z)$ ($e_z < 0.06^\circ$)	0.005	0.010	0.02
Diffuse Pyran Cal (±2 Wm ⁻²)	0.200	0.125	0.25
Temperature Response (ΔT<10° C)	0.050	0.100	0.21
Data Logger (± 9.0 uV)	0.090	0.005	0.09
Cavity Wind effects	0.025	0.025	0.17
Spectral effects	0.010	0.010	0.02
TOTAL	0.376 %	0.516 %	0.638 % (k=2)

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